The 2nd Asian/Australian Rotorcraft Forum (ARF) and The 4th International Basic Research Conference on Rotorcraft Technology (IBRCRT)

Tianjin, China, September 12-14, 2013
Sponsored by

ARF International Executive Committee
Nanjing University of Aeronautics and Astronautics
AVIC Helicopter
AHS International
The Chinese Society for Aeronautics and Astronautics

Call for Papers

The 2nd Asian/Australian Rotorcraft Forum (ARF) and The 4th International Basic Research Conference on Rotorcraft Technology (IBRCRT) will be held in Tianjin, China on Sep. 12-14, 2013 and will be hosted by Nanjing University of Aeronautics and Astronautics (NUAA), China. The relevant information for the 2nd ARF and the 4th IBRCRT can be found at http://arf2013.nuaa.edu.cn. During the forum and conference, there will be an international helicopter exposition – China Helicopter Exposition (http://www.helicopter-china-expo.com).

This forum and conference offers an excellent opportunity for attendees to learn and exchange the latest advances and topics in the following areas, but not limited to: rotorcraft design, aerodynamics, aeroacoustics, dynamics, flight controls and autonomous systems, composites, smart structures, propulsion and drive systems, UAV, system integration, reliability, affordability, HUMS, ice protection, avionics, communications, sensors, safe operations, and especially current rotorcraft development programs.

Abstract Submittal:

Abstract should be written in English; no longer than three pages; presented in sufficient detail to allow the reviewer to determine the quality, scope, significance and current status of the work that will be described in the final paper; include paper title, author(s), name(s), address, phone, fax and e-mail address; and submitted no later than March 30, 2013 at http://arf2013.nuaa.edu.cn . Authors will be notified of final selection by April 30, 2013.

Full Paper Submittal:

Final full papers should be submitted at http://arf2013.nuaa.edu.cn and are due July 30, 2013. Presentations will be given in an open forum and all papers will be published in the conference proceedings. The author is responsible for any necessary clearances and approvals.

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